Module Catalogue
for the Subject
Space Science and Technology
as a Master’s with 1 major
with the degree "Master of Science"
(120 ECTS credits)

Examination regulations version: 2006
Responsible: Institute of Computer Science
Module Catalogue for the Subject
Space Science and Technology
Master's with 1 major, 120 ECTS credits

Contents

The subject is divided into
Content and Objectives of the Programme
Abbreviations used, Conventions, Notes, In accordance with
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Space Science
Space Technology
Internet Technologies
The object-oriented Approach and Java Programming
CanSat Design Lab
Space Dynamics
Spacecraft System Design
Focus
Engineering Track
Scientific Track
Nicht zugeordnet
The Dynamics and Regulation of Systems and Structures
Space Robotics
Space Robotics and Control
Advanced Automation
Team Design Project
Robotics
Space Science and Instrumentation
Space Automation and Regulation
An Introduction to Physical Space Research in Astrophysics, Space Science and Planeto-
logy
Physical Space Advanced Studies in Astrophysics, Space Science and Instrumentati-
on
Atmospheric and Space Physics
The subject is divided into

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Content and Objectives of the Programme
no translation available
Abbreviations used

Course types: **E** = field trip, **K** = colloquium, **O** = conversatorium, **P** = placement/lab course, **R** = project, **S** = seminar, **T** = tutorial, **Ü** = exercise, **V** = lecture

Term: **SS** = summer semester, **WS** = winter semester

Methods of grading: **NUM** = numerical grade, **B/NB** = (not) successfully completed

Regulations: **(L)ASPO** = general academic and examination regulations (for teaching-degree programmes), **FSB** = subject-specific provisions, **SFB** = list of modules

Other: **A** = thesis, **LV** = course(s), **PL** = assessment(s), **TN** = participants, **VL** = prerequisite(s)

Conventions

Unless otherwise stated, courses and assessments will be held in German, assessments will be offered every semester and modules are not creditable for bonus.

Notes

Should there be the option to choose between several methods of assessment, the lecturer will agree with the module coordinator on the method of assessment to be used in the current semester by two weeks after the start of the course at the latest and will communicate this in the customary manner.

Should the module comprise more than one graded assessment, all assessments will be equally weighted, unless otherwise stated below.

Should the assessment comprise several individual assessments, successful completion of the module will require successful completion of all individual assessments.

In accordance with

the general regulations governing the degree subject described in this module catalogue:

frei

associated official publications (FSB (subject-specific provisions)/SFB (list of modules)):

26-Sep-2006 (2006-21)

This module handbook seeks to render, as accurately as possible, the data that is of statutory relevance according to the examination regulations of the degree subject. However, only the FSB (subject-specific provisions) and SFB (list of modules) in their officially published versions shall be legally binding. In the case of doubt, the provisions on, in particular, module assessments specified in the FSB/SFB shall prevail.
Compulsory Courses
(60 ECTS credits)
Space Science
(ECTS credits)
Space Technology

(ECTS credits)
<table>
<thead>
<tr>
<th>Module title</th>
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<tr>
<td>Internet Technologies</td>
<td>10-I-IT-062-m01</td>
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**Module coordinator**
holder of the Chair of Computer Science III

**Module offered by**
Institute of Computer Science

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<th>ECTS</th>
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**Duration**
1 semester

**Module level**
graduate

**Other prerequisites**
--

### Contents
Structure and basic mechanisms of TCP/IP, internet routing, IP network management, wireless access, e.g. 3rd generation mobile networks, GSM technologies.

### Intended learning outcomes
The students master the fundamentals of the structure, architecture and technology of the internet.

### Courses
V + Ü (no information on SWS (weekly contact hours) and course language available)

### Method of assessment
(type, scope, language — if other than German, examination offered — if not every semester, information on whether module is creditable for bonus)
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### Allocation of places
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### Additional information
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### Referred to in LPO I
(examination regulations for teaching-degree programmes)
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<table>
<thead>
<tr>
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<tr>
<td>The object-oriented Approach and Java Programming</td>
<td>10-I-OOA-062-m01</td>
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<td>Swedish partner university in Master’s degree programme</td>
<td>Institute of Computer Science</td>
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<td>Space Science and Technology</td>
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**Duration** 1 semester

**Module level** undergraduate

**Contents**

This module introduces students to the object-oriented programming language Java - not from a theoretical point of view but in a practice-oriented manner with the help of numerous examples and training exercises. The module includes detailed presentations of all parts of the programming language Java as well as the respective ways to use these.

**Intended learning outcomes**

The students are familiar with the basics of the programming language Java and are able to independently develop small applications.

**Courses** (type, number of weekly contact hours, language — if other than German)

Ü + Ü (no information on SWS (weekly contact hours) and course language available)

**Method of assessment** (type, scope, language — if other than German, examination offered — if not every semester, information on whether module is creditable for bonus)

**Allocation of places**

**Additional information**

**Referred to in LPO I** (examination regulations for teaching-degree programmes)
Module title | Abbreviation
--- | ---
CanSat Design Lab | 10-I-CSD-062-m01

Module coordinator | Module offered by
holder of the Chair of Computer Science VIII | Institute of Computer Science

ECTS | Method of grading | Only after succ. compl. of module(s)
--- | --- | ---
4 | (not) successfully completed | --

Duration | Module level | Other prerequisites
--- | --- | ---
1 semester | undergraduate | --

Contents
CanSat (now known as FloatSat) is an interdisciplinary project designed - not only - for SpaceMaster students. It is designed for students with different backgrounds, e. g. in computer science, electronics, mechanical engineering, aerospace technology, physics, mathematics. A satellite project is an interdisciplinary project that requires knowledge and skills in this as well as in numerous other fields. CanSat is thus an ideal platform to combine all available skills in a single project. It covers the design and development of the space segment control software and the ground segment control software: telemetry and telecommanding in wireless communication: space segment - ground segment, electrical subsystem (energy, batteries), mechanical construction.

Intended learning outcomes
The students are able to build and integrate into the inside of the sphere the power unit, a control computer, a payload (camera) and attitude control devices: Gyros and reaction wheel of a pico satellite. The software of a CanSat "satellite" includes a real-time operating system (provided by us), commanding (immediate and time-tagged commands), telemetry (real time and history data), attitude control, power control, payload control, image processing and radio links communication. The ground segment ought to be able to generate and send telecommands and to get and (graphically) display the telemetry.

Courses (type, number of weekly contact hours, language — if other than German)
P (no information on SWS (weekly contact hours) and course language available)

Method of assessment (type, scope, language — if other than German, examination offered — if not every semester, information on whether module is creditable for bonus)
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Allocation of places
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Additional information
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<th>Module level</th>
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<td>1 semester</td>
<td>graduate</td>
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**Contents**

Fundamental principles of astrodynamics, orientation control of satellites, sensors, actuators, control software, example realisations, spin-stabilised satellites, 3-axis stabilised satellites.

**Intended learning outcomes**

The students master the fundamentals of dynamic aspects of the design of spacecraft and are familiar with the essential sensors and actuators as well as their areas of use in spaceflight.

**Courses**

<table>
<thead>
<tr>
<th>type, number of weekly contact hours, language — if other than German</th>
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<td>V + Ü (no information on SWS (weekly contact hours) and course language available)</td>
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**Method of assessment**

(type, scope, language — if other than German, examination offered — if not every semester, information on whether module is creditable for bonus)

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**Allocation of places**

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**Additional information**

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**Referred to in LPO I**

(examination regulations for teaching-degree programmes)

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Module title | Abbreviation
--- | ---
Spacecraft System Design | 10-I-SSD-062-m01

Module coordinator | Module offered by
holder of the Chair of Computer Science VII | Institute of Computer Science

ECTS | Method of grading | Only after succ. compl. of module(s)
--- | --- | ---
7 | numerical grade | --

Duration | Module level | Other prerequisites
--- | --- | ---
1 semester | graduate | --

Contents

Intended learning outcomes
The students master system aspects of the layouting of technical systems. Using the example of spacecraft, major subsystems and their integration into a working whole are being analysed.

Courses (type, number of weekly contact hours, language — if other than German)
V + Ü (no information on SWS (weekly contact hours) and course language available)

Method of assessment (type, scope, language — if other than German, examination offered — if not every semester, information on whether module is creditable for bonus)
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Allocation of places
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Additional information
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Referred to in LPO I (examination regulations for teaching-degree programmes)
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Focus

(30 ECTS credits)
Engineering Track
(30 ECTS credits)
Scientific Track
(30 ECTS credits)
Nicht zugeordnet
(60 ECTS credits)
The Dynamics and Regulation of Systems and Structures
(30 ECTS credits)
Space Robotics
(30 ECTS credits)
Space Robotics and Control
(30 ECTS credits)
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<td>1 semester</td>
<td>graduate</td>
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### Contents

Advanced topics in automation systems as well as instrumentation and control engineering, for example from the field of sensor data processing, actuators, cooperating systems, mission and trajectory planning.

### Intended learning outcomes

The students have an advanced knowledge of selected topics in automation systems. They are able to implement advanced automation systems.

### Courses

Ü (no information on SWS (weekly contact hours) and course language available)

### Method of assessment

(type, scope, language — if other than German, examination offered — if not every semester, information on whether module is creditable for bonus)

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### Allocation of places

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### Additional information

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### Referred to in LPO I

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<td>Team Design Project</td>
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<td>1 semester</td>
<td>graduate</td>
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**Contents**

Multi-disciplinary project in the area of aerospace that covers areas such as mechanical components, electronics and software. In this context, current and relevant topics from research are reviewed.

**Intended learning outcomes**

Students will practise reviewing complex topics in interdisciplinary teams. They will be required to plan, execute and check their work. At the end of the course, they will have created a completely functional system.

**Courses**

P (no information on SWS (weekly contact hours) and course language available)

**Method of assessment**

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**Allocation of places**

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**Additional information**

--

**Referred to in LPO I**

(examination regulations for teaching-degree programmes)

--
Module title | Abbreviation
---|---
Robotics | 10-I-RO-072-m01

Module coordinator | Module offered by
holder of the Chair of Computer Science VII | Institute of Computer Science

ECTS | Method of grading | Only after succ. compl. of module(s)
---|---|---
8 | numerical grade | --

Duration | Module level | Other prerequisites
---|---|---
1 semester | graduate | --

Contents
History, applications and properties of robots, direct kinematics of manipulators: coordinate systems, rotations, homogenous coordinates, axis coordinates, arm equation. Inverse kinematics: solution properties, end effector configuration, numerical and analytical approaches, examples of different robots for analytical approaches. Workspace analysis and trajectory planning, dynamics of manipulators: Lagrange-Euler model, direct and inverse dynamics. Mobile robots: direct and inverse kinematics, propulsion system, tricycle, Ackermann steering, holonomes and non-holonome restrictions, kinematic classification of mobile robots, posture kinematic model. Movement control and path planning: roadmap methods, cell decomposition methods, potential field methods. Sensors: position sensors, speed sensors, distance sensors.

Intended learning outcomes
The students master the fundamentals of robot manipulators and vehicles and are, in particular, familiar with their kinematics and dynamics as well as the planning of paths and task execution.

Courses (type, number of weekly contact hours, language — if other than German)
V + Ü (no information on SWS (weekly contact hours) and course language available)

Method of assessment (type, scope, language — if other than German, examination offered — if not every semester, information on whether module is creditable for bonus)
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Allocation of places
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Additional information
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Referred to in LPO I (examination regulations for teaching-degree programmes)
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Space Science and Instrumentation
(30 ECTS credits)
Space Automation and Regulation

(30 ECTS credits)
An Introduction to Physical Space Research in Astrophysics, Space Science and Planetology

(30 ECTS credits)
Physical Space Advanced Studies in Astrophysics, Space Science and Instrumentation

(30 ECTS credits)
Atmospheric and Space Physics
(30 ECTS credits)