



# Module Catalogue

for the Subject

# Space Science and Technology

as a Master's with 1 major  
with the degree "Master of Science"  
(120 ECTS credits)

Examination regulations version: 2005  
Responsible: Faculty of Mathematics and Computer Science

## Contents

The subject is divided into	3
Abbreviations used, Conventions, Notes, In accordance with	4
Compulsory Courses	5
Space Science	6
Space Technology	7
Focus	8
Engineering Track	9
The Dynamics and Regulation of Systems and Structures	10
Space Robotics	11
Space Robotics and Control	12
Advanced Automation	13
Team Design Project	14
Robotics	15
Astronautics Seminar	16
Space Science and Instrumentation	17
Space Automation and Regulation	18
Scientific Track	19
An Introduction to Physical Space Research in Astrophysics, Space Science and Plane-	
tology	20
Physical Space Advanced Studies in Astrophysics, Space Science and Instrumentati-	
on	21
Atmospheric and Space Physics	22
Nicht zugeordnet	23

## The subject is divided into

section / sub-section	ECTS credits	starting page
Compulsory Courses	60	5
Space Science	30	6
Space Technology	30	7
Focus	30	8
Engineering Track	30	9
The Dynamics and Regulation of Systems and Structures	30	10
Space Robotics	30	11
Space Robotics and Control	30	12
Space Science and Instrumentation	30	17
Space Automation and Regulation	30	18
Scientific Track	30	19
An Introduction to Physical Space Research in Astrophysics, Space Science and Planetology	30	20
Physical Space Advanced Studies in Astrophysics, Space Science and Instrumentation	30	21
Atmospheric and Space Physics	30	22
Nicht zugeordnet	60	23

## Abbreviations used

Course types: **E** = field trip, **K** = colloquium, **O** = conversatorium, **P** = placement/lab course, **R** = project, **S** = seminar, **T** = tutorial, **Ü** = exercise, **V** = lecture

Term: **SS** = summer semester, **WS** = winter semester

Methods of grading: **NUM** = numerical grade, **B/NB** = (not) successfully completed

Regulations: **(L)ASPO** = general academic and examination regulations (for teaching-degree programmes), **FSB** = subject-specific provisions, **SFB** = list of modules

Other: **A** = thesis, **LV** = course(s), **PL** = assessment(s), **TN** = participants, **VL** = prerequisite(s)

## Conventions

Unless otherwise stated, courses and assessments will be held in German, assessments will be offered every semester and modules are not creditable for bonus.

## Notes

Should there be the option to choose between several methods of assessment, the lecturer will agree with the module coordinator on the method of assessment to be used in the current semester by two weeks after the start of the course at the latest and will communicate this in the customary manner.

Should the module comprise more than one graded assessment, all assessments will be equally weighted, unless otherwise stated below.

Should the assessment comprise several individual assessments, successful completion of the module will require successful completion of all individual assessments.

## In accordance with

the general regulations governing the degree subject described in this module catalogue:

**frei**

associated official publications (FSB (subject-specific provisions)/SFB (list of modules)):

**26-Sep-2006 (2006-21)**

This module handbook seeks to render, as accurately as possible, the data that is of statutory relevance according to the examination regulations of the degree subject. However, only the FSB (subject-specific provisions) and SFB (list of modules) in their officially published versions shall be legally binding. In the case of doubt, the provisions on, in particular, module assessments specified in the FSB/SFB shall prevail.

## Compulsory Courses

(60 ECTS credits)

# Space Science

(30 ECTS credits)

# Space Technology

(30 ECTS credits)

## **Focus**

(30 ECTS credits)



## **Engineering Track**

(30 ECTS credits)

# The Dynamics and Regulation of Systems and Structures

(30 ECTS credits)

# Space Robotics

(30 ECTS credits)

# Space Robotics and Control

(30 ECTS credits)

<b>Module title</b>		<b>Abbreviation</b>
Advanced Automation		10-I-AA-072-m01
<b>Module coordinator</b>		<b>Module offered by</b>
holder of the Chair of Computer Science VII		Institute of Computer Science
<b>ECTS</b>	<b>Method of grading</b>	<b>Only after succ. compl. of module(s)</b>
8	numerical grade	--
<b>Duration</b>	<b>Module level</b>	<b>Other prerequisites</b>
1 semester	graduate	--
<b>Contents</b>		
Advanced topics in automation systems as well as instrumentation and control engineering, for example from the field of sensor data processing, actuators, cooperating systems, mission and trajectory planning.		
<b>Intended learning outcomes</b>		
The students have an advanced knowledge of selected topics in automation systems. They are able to implement advanced automation systems.		
<b>Courses</b> (type, number of weekly contact hours, language – if other than German)		
Ü (no information on SWS (weekly contact hours) and course language available)		
<b>Method of assessment</b> (type, scope, language – if other than German, examination offered – if not every semester, information on whether module is creditable for bonus)		
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<b>Allocation of places</b>		
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<b>Additional information</b>		
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<b>Referred to in LPO I</b> (examination regulations for teaching-degree programmes)		
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<b>Module title</b>		<b>Abbreviation</b>
Team Design Project		10-I-TDP-072-m01
<b>Module coordinator</b>		<b>Module offered by</b>
holder of the Chair of Computer Science VII		Institute of Computer Science
<b>ECTS</b>	<b>Method of grading</b>	<b>Only after succ. compl. of module(s)</b>
10	numerical grade	--
<b>Duration</b>	<b>Module level</b>	<b>Other prerequisites</b>
1 semester	graduate	--
<b>Contents</b>		
Multi-disciplinary project in the area of aerospace that covers areas such as mechanical components, electronics and software. In this context, current and relevant topics from research are reviewed.		
<b>Intended learning outcomes</b>		
Students will practise reviewing complex topics in interdisciplinary teams. They will be required to plan, execute and check their work. At the end of the course, they will have created a completely functional system.		
<b>Courses</b> (type, number of weekly contact hours, language – if other than German)		
P (no information on SWS (weekly contact hours) and course language available)		
<b>Method of assessment</b> (type, scope, language – if other than German, examination offered – if not every semester, information on whether module is creditable for bonus)		
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<b>Allocation of places</b>		
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<b>Additional information</b>		
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<b>Referred to in LPO I</b> (examination regulations for teaching-degree programmes)		
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<b>Module title</b>		<b>Abbreviation</b>
Robotics		10-I-RO-072-m01
<b>Module coordinator</b>		<b>Module offered by</b>
holder of the Chair of Computer Science VII		Institute of Computer Science
<b>ECTS</b>	<b>Method of grading</b>	<b>Only after succ. compl. of module(s)</b>
8	numerical grade	--
<b>Duration</b>	<b>Module level</b>	<b>Other prerequisites</b>
1 semester	graduate	--
<b>Contents</b>		
<p>History, applications and properties of robots, direct kinematics of manipulators: coordinate systems, rotations, homogenous coordinates, axis coordinates, arm equation. Inverse kinematics: solution properties, end effector configuration, numerical and analytical approaches, examples of different robots for analytical approaches. Workspace analysis and trajectory planning, dynamics of manipulators: Lagrange-Euler model, direct and inverse dynamics. Mobile robots: direct and inverse kinematics, propulsion system, tricycle, Ackermann steering, holonomes and non-holonomie restrictions, kinematic classification of mobile robots, posture kinematic model. Movement control and path planning: roadmap methods, cell decomposition methods, potential field methods. Sensors: position sensors, speed sensors, distance sensors.</p>		
<b>Intended learning outcomes</b>		
<p>The students master the fundamentals of robot manipulators and vehicles and are, in particular, familiar with their kinematics and dynamics as well as the planning of paths and task execution.</p>		
<b>Courses</b> (type, number of weekly contact hours, language — if other than German)		
V + Ü (no information on SWS (weekly contact hours) and course language available)		
<b>Method of assessment</b> (type, scope, language — if other than German, examination offered — if not every semester, information on whether module is creditable for bonus)		
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<b>Allocation of places</b>		
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<b>Additional information</b>		
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<b>Module title</b>		<b>Abbreviation</b>
Astronautics Seminar		10-I-SR-072-m01
<b>Module coordinator</b>		<b>Module offered by</b>
Dean of Studies Informatik (Computer Science)		Institute of Computer Science
<b>ECTS</b>	<b>Method of grading</b>	<b>Only after succ. compl. of module(s)</b>
5	numerical grade	--
<b>Duration</b>	<b>Module level</b>	<b>Other prerequisites</b>
1 semester	graduate	--
<b>Contents</b>		
Independent review of a current topic in computer science based on literature and, where applicable, software with written and oral presentation.		
<b>Intended learning outcomes</b>		
The students are able to independently review a current topic in aerospace information technology, to summarise the main aspects in written form and to orally present these in an appropriate way.		
<b>Courses</b> (type, number of weekly contact hours, language – if other than German)		
S (no information on SWS (weekly contact hours) and course language available)		
<b>Method of assessment</b> (type, scope, language – if other than German, examination offered – if not every semester, information on whether module is creditable for bonus)		
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<b>Allocation of places</b>		
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# Space Science and Instrumentation

(30 ECTS credits)

# Space Automation and Regulation

(30 ECTS credits)

## **Scientific Track**

(30 ECTS credits)

# **An Introduction to Physical Space Research in Astrophysics, Space Science and Planetology**

(30 ECTS credits)

# **Physical Space Advanced Studies in Astrophysics, Space Science and Instrumentation**

(30 ECTS credits)

# Atmospheric and Space Physics

(30 ECTS credits)

## **Nicht zugeordnet**

(60 ECTS credits)