Module description

<table>
<thead>
<tr>
<th>Module title</th>
<th>Abbreviation</th>
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<tbody>
<tr>
<td>Robotics 2</td>
<td>10-I=RO2-152-m01</td>
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<table>
<thead>
<tr>
<th>Module coordinator</th>
<th>Module offered by</th>
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<tbody>
<tr>
<td>holder of the Chair of Computer Science VII</td>
<td>Institute of Computer Science</td>
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<table>
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<tr>
<th>ECTS</th>
<th>Method of grading</th>
<th>Only after succ. compl. of module(s)</th>
</tr>
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<tbody>
<tr>
<td>8</td>
<td>numerical grade</td>
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<tr>
<th>Duration</th>
<th>Module level</th>
<th>Other prerequisites</th>
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<tbody>
<tr>
<td>1 semester</td>
<td>graduate</td>
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**Contents**

Foundations of dynamic systems, controllability and observability, controller design through pole assignment: feedback and feed-forward, state observer, feedback with state observer, time discrete systems, stochastic systems: foundations of stochastics, random processes, stochastic dynamic systems, Kalman filter: derivation, initialising, application examples, problems of Kalman filters, extended Kalman filter.

**Intended learning outcomes**

The students master all fundamentals that are necessary to understand Kalman filters and their use in applications of robotics. The students possess a knowledge of advanced controller and observer methods and recognise the connections between the dual pairs controllability - observability as well as controller design and observer design. They also recognise the relationship between the Kalman filter as a state estimator and an observer.

**Courses** (type, number of weekly contact hours, language — if other than German)

V (4) + Ü (2)

**Method of assessment** (type, scope, language — if other than German, examination offered — if not every semester, information on whether module is creditable for bonus)

written examination (approx. 60 to 90 minutes)
creditable for bonus

**Allocation of places**

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**Additional information**

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**Referred to in LPO I** (examination regulations for teaching-degree programmes)

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**Module appears in**

- Master's degree (1 major) Space Science and Technology (2015)
- First state examination for the teaching degree Gymnasium Computer Science (2015)
- Master's degree (1 major) Computer Science (2016)
- Master's degree (1 major) Mathematics (2016)
- Master's degree (1 major) Computational Mathematics (2016)
- Master's teaching degree Gymnasium MINT Teacher Education PLUS, Elite Network Bavaria (ENB) (2016)
- Supplementary course MINT Teacher Education PLUS, Elite Network Bavaria (ENB) (2016)
- Master's degree (1 major) Computer Science (2017)
- Master's degree (1 major) Computer Science (2018)
- Master's degree (1 major) Computational Mathematics (2019)
- Master's degree (1 major) Mathematics (2019)
- Master's teaching degree Gymnasium MINT Teacher Education PLUS, Elite Network Bavaria (ENB) (2020)
- Supplementary course MINT Teacher Education PLUS, Elite Network Bavaria (ENB) (2020)