

<b>Module title</b>		<b>Abbreviation</b>
Robotics 1		10-I=RO1-122-m01
<b>Module coordinator</b>		<b>Module offered by</b>
holder of the Chair of Computer Science VII		Institute of Computer Science
<b>ECTS</b>	<b>Method of grading</b>	<b>Only after succ. compl. of module(s)</b>
8	numerical grade	--
<b>Duration</b>	<b>Module level</b>	<b>Other prerequisites</b>
1 semester	graduate	--
<b>Contents</b>		
<p>History, applications and properties of robots, direct kinematics of manipulators: coordinate systems, rotations, homogenous coordinates, axis coordinates, arm equation. Inverse kinematics: solution properties, end effector configuration, numerical and analytical approaches, examples of different robots for analytical approaches. Workspace analysis and trajectory planning, dynamics of manipulators: Lagrange-Euler model, direct and inverse dynamics. Mobile robots: direct and inverse kinematics, propulsion system, tricycle, Ackermann steering, holonomes and non-holonomie restrictions, kinematic classification of mobile robots, posture kinematic model. Movement control and path planning: roadmap methods, cell decomposition methods, potential field methods. Sensors: position sensors, speed sensors, distance sensors.</p>		
<b>Intended learning outcomes</b>		
<p>The students master the fundamentals of robot manipulators and vehicles and are, in particular, familiar with their kinematics and dynamics as well as the planning of paths and task execution.</p>		
<b>Courses</b> (type, number of weekly contact hours, language — if other than German)		
V + T (no information on SWS (weekly contact hours) and course language available)		
<b>Method of assessment</b> (type, scope, language — if other than German, examination offered — if not every semester, information on whether module is creditable for bonus)		
<p>written examination (approx. 60 to 90 minutes) Language of assessment: English</p>		
<b>Allocation of places</b>		
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<b>Additional information</b>		
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<b>Referred to in LPO I</b> (examination regulations for teaching-degree programmes)		
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<b>Module appears in</b>		
<p>Master's degree (1 major) Space Science and Technology (2012) Master's degree (1 major) Computer Science (2014)</p>		