

Module description

Module title					Abbreviation
Robotics 10-I=RO-141-mo1					
Module coordinator				Module offered by	
holder of the Chair of Computer Scienc			ce VII	Institute of Computer Science	
ECTS Method of grading		od of grading	Only after succ. compl. of module(s)		
8	nume	rical grade			
Duration		Module level	Other prerequisites		
1 semester		graduate			
Contents					
tor configuration, numerical and analytical approaches, examples of different robots for analytical approaches. Workspace analysis and trajectory planning, dynamics of manipulators: Lagrange-Euler model, direct and inverse dynamics. Mobile robots: direct and inverse kinematics, propulsion system, tricycle, Ackermann steering, holonomes and non-holonome restrictions, kinematic classification of mobile robots, posture kinematic model. Movement control and path planning: roadmap methods, cell decomposition methods, potential field methods. Sensors: position sensors, speed sensors, distance sensors. Intended learning outcomes The students master the fundamentals of robot manipulators and vehicles and are, in particular, familiar with their kinematics and dynamics as well as the planning of paths and task execution.					
Courses (type, number of weekly contact hours, language — if other than German)					
V + Ü (no information on SWS (weekly contact hours) and course language available)					
Method of assessment (type, scope, language — if other than German, examination offered — if not every semester, information on whether module is creditable for bonus)					
written examination (approx. 60 to 120 minutes); if announced by the lecturer at the beginning of the course, the written examination can be replaced by an oral examination of one candidate each (approx. 20 minutes) or an oral examination in groups (groups of 2, approx. 30 minutes) Language of assessment: German, English					
Allocation of places					
Additional information					
					
Workload					
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Teaching cycle					
Referred to in LPO I (examination regulations for teaching-degree programmes)					
Modul	e annea	nrs in			

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Bachelor' degree (1 major) Aerospace Computer Science (2014)