

| | | |
|--|--------------------------|--|
| Module title | | Abbreviation |
| Robotics | | 10-I=RO-102-m01 |
| Module coordinator | | Module offered by |
| holder of the Chair of Computer Science VII | | Institute of Computer Science |
| ECTS | Method of grading | Only after succ. compl. of module(s) |
| 8 | numerical grade | -- |
| Duration | Module level | Other prerequisites |
| 1 semester | graduate | Where applicable, prerequisites as specified by the lecturer at the beginning of the course (e. g. completion of exercises). |
| Contents | | |
| <p>History, applications and properties of robots, direct kinematics of manipulators: coordinate systems, rotations, homogenous coordinates, axis coordinates, arm equation. Inverse kinematics: solution properties, end effector configuration, numerical and analytical approaches, examples of different robots for analytical approaches. Workspace analysis and trajectory planning, dynamics of manipulators: Lagrange-Euler model, direct and inverse dynamics. Mobile robots: direct and inverse kinematics, propulsion system, tricycle, Ackermann steering, holonomes and non-holonomie restrictions, kinematic classification of mobile robots, posture kinematic model. Movement control and path planning: roadmap methods, cell decomposition methods, potential field methods. Sensors: position sensors, speed sensors, distance sensors.</p> | | |
| Intended learning outcomes | | |
| The students master the fundamentals of robot manipulators and vehicles and are, in particular, familiar with their kinematics and dynamics as well as the planning of paths and task execution. | | |
| Courses (type, number of weekly contact hours, language — if other than German) | | |
| V + Ü (no information on SWS (weekly contact hours) and course language available) | | |
| Method of assessment (type, scope, language — if other than German, examination offered — if not every semester, information on whether module is creditable for bonus) | | |
| <p>written examination (approx. 80 to 90 minutes). If announced by the lecturer by four weeks prior to the examination date, the written examination can be replaced by an oral examination of one candidate each or an oral examination in groups. A 80 to 90 minute written examination is equivalent to a 20 minute (approx.) oral examination of one candidate each, a 30 minute (approx.) oral examination in groups of 2 and a 40 minute (approx.) oral examination in groups of 3.</p> <p>Language of assessment: German, English if agreed upon with the examiner</p> | | |
| Allocation of places | | |
| -- | | |
| Additional information | | |
| -- | | |
| Workload | | |
| -- | | |
| Teaching cycle | | |
| -- | | |
| Referred to in LPO I (examination regulations for teaching-degree programmes) | | |
| -- | | |
| Module appears in | | |
| <p>Bachelor' degree (1 major) Aerospace Computer Science (2009) Bachelor' degree (1 major) Aerospace Computer Science (2011) Master's degree (1 major) Computer Science (2010) Master's degree (1 major) Mathematics (2012) Master's degree (1 major) Mathematics (2010)</p> | | |

Master's degree (1 major) Computational Mathematics (2012)

First state examination for the teaching degree Gymnasium Computer Science (2009)